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APPLICATION NO.		FILING DATE	FIRST NAMED INVENTOR	ATTORNEY DOCKET NO.	CONFIRMATION NO.
09/814,099		03/22/2001	Masanori Ikari	010270	2044
23850	7590	02/18/2004		EXAMINER	
ARMSTRONG, KRATZ, QUINTOS, HANSON & BROOKS, LLP				NGUYEN, THU V	
1725 K STR SUITE 1000		V		ART UNIT	PAPER NUMBER
WASHING	WASHINGTON, DC 20006			3661	
				DATE MAILED: 02/18/2004	4

Please find below and/or attached an Office communication concerning this application or proceeding.

	Application No.	Applicant(s)	- / \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \
	''		
Advisory Action	09/814,099	IKARI, MASANORI	
•	Examiner	Art Unit	
	Thu Nguyen	3661	
The MAILING DATE of this communication appe	ears on the cover sheet with the c	orrespondence address	s
THE REPLY FILED 21 January 2004 FAILS TO PLACE Therefore, further action by the applicant is required to avinal rejection under 37 CFR 1.113 may only be either: (1 condition for allowance; (2) a timely filed Notice of Appea Examination (RCE) in compliance with 37 CFR 1.114.	void abandonment of this applica ) a timely filed amendment which	ation. A proper reply to h places the application	a n in
PERIOD FOR RE	EPLY [check either a) or b)]		
a) $\square$ The period for reply expires $\underline{3}$ months from the mailing date			
b) The period for reply expires on: (1) the mailing date of this A no event, however, will the statutory period for reply expire I ONLY CHECK THIS BOX WHEN THE FIRST REPLY WAS 706.07(f).	later than SIX MONTHS from the mailin S FILED WITHIN TWO MONTHS OF TH	g date of the final rejection. HE FINAL REJECTION. See	MPEP
Extensions of time may be obtained under 37 CFR 1.136(a). The see have been filed is the date for purposes of determining the period of see under 37 CFR 1.17(a) is calculated from: (1) the expiration date of 2) as set forth in (b) above, if checked. Any reply received by the Office mely filed, may reduce any earned patent term adjustment. See 37 C	of extension and the corresponding amo the shortened statutory period for reply ce later than three months after the mai	ount of the fee. The appropriation originally set in the final Office.	ate extension ce action; or
<ol> <li>A Notice of Appeal was filed on Appellant's 37 CFR 1.192(a), or any extension thereof (37 CFF</li> </ol>			
2. The proposed amendment(s) will not be entered be	ecause:		
(a) X they raise new issues that would require further	er consideration and/or search (	see NOTE below);	
(b) they raise the issue of new matter (see Note b	pelow);		
(c)  they are not deemed to place the application in issues for appeal; and/or	n better form for appeal by mate	rially reducing or simplif	fying the
(d) they present additional claims without canceli	ng a corresponding number of fi	inally rejected claims.	
NOTE: See Continuation Sheet.			
<ol> <li>Applicant's reply has overcome the following reject</li> </ol>	tion(s):		
<ol> <li>Newly proposed or amended claim(s) would canceling the non-allowable claim(s).</li> </ol>	be allowable if submitted in a se	parate, timely filed ame	endment
5. ☐ The a) ☐ affidavit, b) ☐ exhibit, or c) ☐ request for application in condition for allowance because: Se		dered but does NOT pla	ace the
<ol> <li>The affidavit or exhibit will NOT be considered becaraised by the Examiner in the final rejection.</li> </ol>	ause it is not directed SOLELY t	o issues which were ne	wly
7.  For purposes of Appeal, the proposed amendment explanation of how the new or amended claims we	· · · · · · · · · · · · · · · · · · ·	· <del></del>	an
The status of the claim(s) is (or will be) as follows:	, .		
Claim(s) allowed: <u>2,3,12 and 13</u> .	•		
Claim(s) objected to:			
Claim(s) rejected: <u>1 and 11</u> .			
Claim(s) withdrawn from consideration: 4-10.			
B.⊠ The drawing correction filed on <u>22 August 2002</u> is a	a)⊠ approved or b)□ disappr	oved by the Examiner.	
9. Note the attached Information Disclosure Statemer		-	
0. ☐ Other:		<u></u> -	
· · · · · · · · · · · · · · · · · · ·		Ugugarlen	
		Thu Nguyen Primary Examiner Art Unit: 3661	

U.S. Patent and Trademark Office PTOL-303 (Rev. 11-03) Continuation of 2. NOTE: the correction to claims 1, and 11 change the scope of the claim. Such the changes need further consideration

Continuation of 5. does NOT place the application in condition for allowance because: in response to applicant's argument on page 18; page 19, last paragraph; page 20, first and second paragraph, Kinugawa does teach the load judging portion, because, claim 1 claims a load judging portion that detects whether the vehicle is under excavation. In col.14, lines 34-37, in combination with col.19, lines 1-6, Kinugawa teaches classification of works of the hydraulic excavator based on the data detected from the sensors sensing operation of the boom, the bucket, etc. The classification of works is clearly a load judging portion because the classification procedure of Kinugawa can recognize the excavation condition of the vehicle (col.25-30 of Kinugawa teaches how the operating condition (the excavating condition. the scattering condition, etc.) are recognized); specifically, col.26, lines 45-56 shows how the excavating condition (the simple digging) of the vehicle is recognized. Therefore, the classification of work discrimination section 41' (fig.3) is the claimed load judging section. Although the applicant asserts that the section 41' is not the same as the loading judging portion, however, both the explanation and the claimed language describing the loading judging portion fail to highlight the difference between the portion 41' (fig.2) of Kinugawa and the load judging section of the present application. In response to applicant's argument on page 19, first two paragraphs, page 20, last paragraph; page 21, first two paragraphs, independent claim 11 just claims the automatic excavation control means as a means capable of outputting the axcavation command value to each of the control valves. In col.35, lines 35-40, Kinugawa clearly teaches an automatic excavation control means which automatically control the vehicle suitable to the detected classification of works. Since one classification of works is simple digging (simple excavation) (col.30, lines 41-42), and since the automatic excavatin control means of Kimugawa is capable of sending control parameters to the pump according to the excavation status (col.33, lines 35-67, especially in table I), further, since the hydraulic pump actually control the valves (col.17, lines 58-67; col.18, lines 1-2), the automatic excavation control means of Kinugawa is clearly capable of outputting the control command to the valves through the control of the pumps 2 and 3 (fig.1). The cited section in page 20, last paragraph, and page 21, first two paragraphs shows returning the operating levers 17-22 to neutral (zero position from an operating condition (note that the lever 17 (fig.1) represents the boom lever), since Kinugawa teaches detecting the data from the levers every predetermined period of time and use such the data in determining excavation condition of the vehicle (col.27, lines 30-45), Kinugawa obviously teaches the capability to detect excavation condition (the classification state of the vehicle) when the boom lever changes from a position to the neutral position.